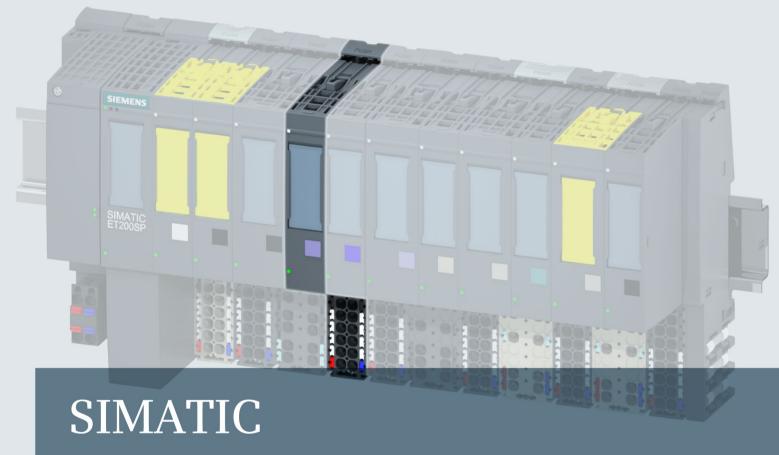
# **SIEMENS**



**ET 200SP** 

Analog input module AI 2xU/I 2-/4-wire HF (6ES7134-6HB00-0CA1)

Manual



Answers for industry.

# **SIEMENS**

**SIMATIC** 

ET 200SP Analog input module Al 2xU/I 2-/4-wire HF (6ES7134-6HB00-0CA1)

Manual

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#### Legal information

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indicates that death or severe personal injury will result if proper precautions are not taken.

#### **A**WARNING

indicates that death or severe personal injury may result if proper precautions are not taken.

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indicates that minor personal injury can result if proper precautions are not taken.

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indicates that property damage can result if proper precautions are not taken.

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#### **Qualified Personnel**

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

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We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

## **Preface**

#### Purpose of the documentation

This manual supplements the ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293) system manual.

Functions that generally relate to the system are described in this system manual.

The information provided in this manual and in the system/function manuals supports you in commissioning the system.

#### Conventions

CPU: When the term "CPU" is used in this manual, it applies to the CPUs of the S7-1500 automation system as well as to the CPUs/interface modules of the ET 200SP distributed I/O system.

STEP 7: In this documentation, "STEP 7" is used as a synonym for all versions of the configuration and programming software "STEP 7 (TIA Portal)".

Please also observe notes marked as follows:

#### Note

A note contains important information on the product described in the documentation, on the handling of the product or on the section of the documentation to which particular attention should be paid.

#### Security information

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To stay informed about product updates as they occur, sign up for a product-specific newsletter. You can find more information on the Internet (http://support.automation.siemens.com).

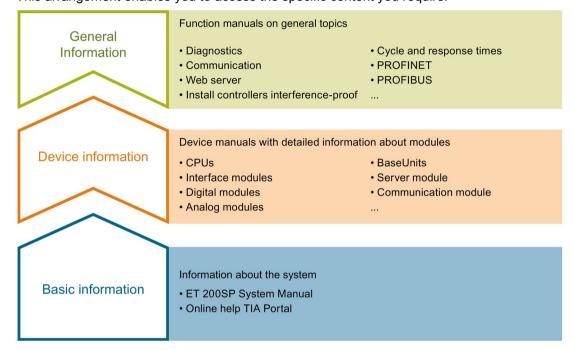
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Guide to documentation

The documentation for the SIMATIC ET 200SP distributed I/O system is arranged into three areas.

This arrangement enables you to access the specific content you require.



#### **Basic information**

The system manual describes in detail the configuration, installation, wiring and commissioning of the SIMATIC ET 200SP. distributed I/O system. The STEP 7 online help supports you in the configuration and programming.

#### **Device information**

Product manuals contain a compact description of the module-specific information, such as properties, terminal diagrams, characteristics and technical specifications.

#### General information

The function manuals contain detailed descriptions on general topics regarding the SIMATIC ET 200SP distributed I/O system, e.g. diagnostics, communication, Web server, designing interference-free controllers.

You can download the documentation free of charge from the Internet (<a href="http://w3.siemens.com/mcms/industrial-automation-systems-simatic/en/manual-overview/tech-doc-et200/Pages/Default.aspx">http://w3.siemens.com/mcms/industrial-automation-systems-simatic/en/manual-overview/tech-doc-et200/Pages/Default.aspx</a>).

Changes and supplements to the manuals are documented in a Product Information.

You can download the product information free of charge from the Internet (https://support.industry.siemens.com/cs/us/en/view/73021864).

#### Manual Collection ET 200SP

The Manual Collection contains the complete documentation on the SIMATIC ET 200SP distributed I/O system gathered together in one file.

You can find the Manual Collection on the Internet (http://support.automation.siemens.com/WW/view/en/84133942).

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#### "mySupport" - CAx Data

In the CAx Data area of "mySupport", you can have access the latest product data for your CAx or CAe system.

You configure your own download package with a few clicks.

In doing so you can select:

- Product images, 2D dimension drawings, 3D models, internal circuit diagrams, EPLAN macro files
- Manuals, characteristics, operating manuals, certificates
- Product master data

You can find "mySupport" - CAx Data in the Internet (http://support.industry.siemens.com/my/ww/en/CAxOnline).

## **Application examples**

The application examples support you with various tools and examples for solving your automation tasks. Solutions are shown in interplay with multiple components in the system - separated from the focus in individual products.

You can find the application examples on the Internet (https://support.industry.siemens.com/sc/ww/en/sc/2054).

#### **TIA Selection Tool**

With the TIA Selection Tool, you can select, configure and order devices for Totally Integrated Automation (TIA).

This tool is the successor of the SIMATIC Selection Tool and combines the known configurators for automation technology into one tool.

With the TIA Selection Tool, you can generate a complete order list from your product selection or product configuration.

You can find the TIA Selection Tool on the Internet (http://w3.siemens.com/mcms/topics/en/simatic/tia-selection-tool).

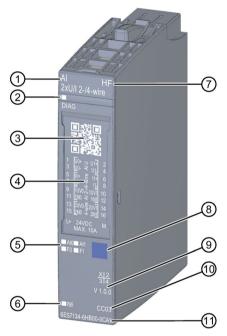
Product overview

## 2.1 Properties

#### Article number

6ES7134-6HB00-0CA1

#### View of the module



- 1 Module type and name
- ② LED for diagnostics
- 3 2D matrix code
- 4 Wiring diagram
- (5) LEDs for channel status
- 6 LED for supply voltage
- 7 Function class
- 8 Color coding module type
- 9 Function and firmware version
- 10 Color code for selecting the color identification labels
- 1 Article number

Image 2-1 View of the module AI 2×U/I 2-/4-wire HF

#### 2.1 Properties

#### **Properties**

The module has the following technical properties:

- Analog input module with 2 inputs
- Resolution: Up to 16 bits including sign
- Single channel electrical isolation
- Voltage measurement type can be set per channel
- Current measuring type can be set per channel (for 2-wire or 4-wire transducer)
- Configurable diagnostics (per channel)

The module supports the following functions:

- · Firmware update
- I&M identification data
- Configuration in RUN
- PROFlenergy
- Calibration in runtime
- Isochronous mode (PROFINET IO only)
- Value status (PROFINET IO only)

Table 2-1 Version dependencies of other module functions

| Function                           | Product version of the module as of | Firmware version of the module as of |
|------------------------------------|-------------------------------------|--------------------------------------|
| Measuring range adjustment         | 1                                   | V2.0.0                               |
| Scaling of measured values         | 1                                   | V2.0.0                               |
| Module-internal shared input (MSI) | 1                                   | V2.0.0                               |

You can configure the module with STEP 7 (TIA Portal) and with a GSD file 1.

#### **Accessories**

The following accessories must be ordered separately:

- Labeling strips
- · Color identification labels
- Reference identification label
- Shield connector

#### See also

You can find additional information on the accessories in the ET 200SP distributed I/O system system manual.

<sup>&</sup>lt;sup>1</sup> Version required for STEP 7: V5.5 SP4 HF7

Wiring

## 3.1 Wiring and block diagram

This section includes the block diagram of the AI 2xU/I 2-/4-wire HF module with the various terminal assignments for a 2- und 4-wire connection.

You can find information on wiring the BaseUnit in the ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293) system manual.

#### Note

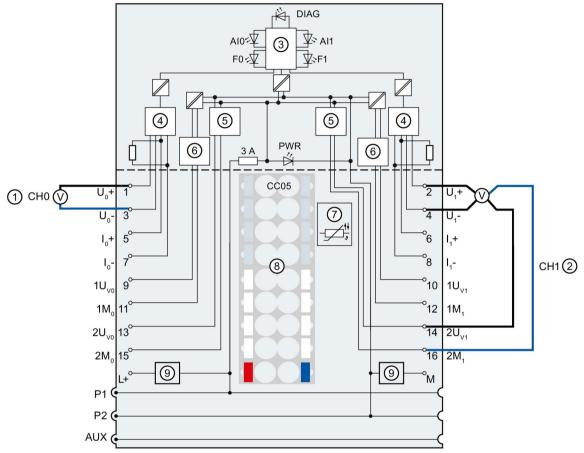
You can use and combine the different wiring options for all channels.

#### Note

The load group of the module must begin with a light-colored BaseUnit. Keep this in mind also during the configuration.

#### Wiring: Voltage measurement 2-wire and 4-wire connection

The following figure shows the block diagram and an example of the terminal assignment of the analog input module AI 2xU/I 2-/4-wire HF on the BaseUnit BU type A0/A1.

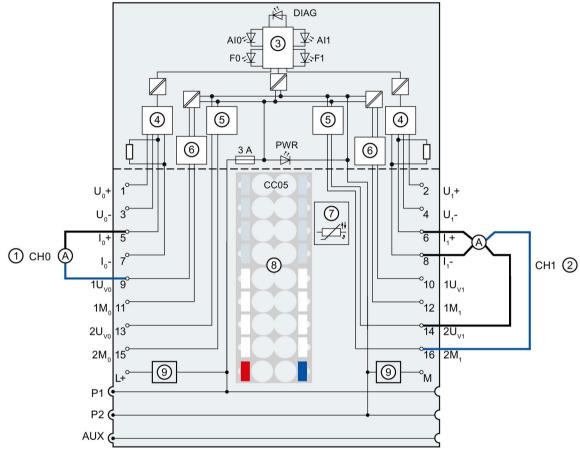


| $\overline{}$    |   |                  |  |
|------------------|---|------------------|--|
| 1                | 2-wire connection for voltage measurement   | <b>I</b> n+      | Current input positive, channel n  |
| 2                | 4-wire connection for voltage measurement   | I <sub>n</sub> - | Current input negative, channel n  |
| 3                | Backplane bus interface   | $U_{Vn}$         | Supply voltage, channel n  |
| 4                | Analog-to-digital converter (ADC)   | Mn               | Reference ground to U <sub>Vn</sub> , channel n  |
| ⑤                | Current limitation (4-wire)   | L+               | 24 V DC (infeed only with light-colored BaseUnit)  |
| 6                | Current limitation (2-wire)   | P1, P2, AUX      | Internal self-assembling voltage buses<br>Connection to left (dark-colored BaseUnit)<br>Connection to left interrupted (light-colored<br>BaseUnit) |
| 7                | Temperature recording for BU type A1 only (function cannot be used for this module) | DIAG             | Diagnostics LED (green, red)   |
| 8                | Color-coded label with color code CC05 (optional)                                   | AI0, AI1         | Channel status LED (green)   |
| 9                | Filter connection supply voltage (only when light-colored BaseUnit is present)      | F0, F1           | Channel fault LED (red)  |
| U <sub>n</sub> + | Voltage input positive, channel n   | PWR              | Power LED (green)  |
| Un-              | Voltage input negative, channel n   |                  |  |

Image 3-1 Wiring and block diagram for voltage measurement 2-wire and 4-wire connection

#### Wiring: Current measurement 2-wire and 4-wire connection (2-wire and 4-wire transducer)

The following figure shows the block diagram and an example of the terminal assignment of the analog input module AI 2xU/I 2-/4-wire HF on the BaseUnit BU type A0/A1.



| 1                | 2-wire connection for current measurement (2-wire transducer)                       | U <sub>n</sub> + | Voltage input positive, channel n                       |
|------------------|---|------------------|---|
| 2                | 4-wire connection for current measurement (4-wire transducer)                       | U <sub>n</sub> - | Voltage input negative, channel n                       |
| 3                | Backplane bus interface   | $U_{Vn}$         | Supply voltage, channel n                               |
| 4                | Analog-to-digital converter (ADC)   | $M_n$            | Reference ground to U <sub>Vn</sub> , channel n         |
| (5)              | Current limitation (4-wire)   | L+               | 24 V DC (infeed only with light-colored BaseUnit)       |
| 6                | Current limitation (2-wire)   | P1, P2, AUX      | Internal self-assembling voltage buses                  |
|                  |   |                  | Connection to left (dark-colored BaseUnit)              |
| _                |   |                  | Connection to left interrupted (light-colored BaseUnit) |
| 7                | Temperature recording for BU type A1 only (function cannot be used for this module) | DIAG             | Diagnostics LED (green, red)                            |
| 8                | Color-coded label with color code CC05 (optional)                                   | AI0, AI1         | Channel status LED (green)                              |
| 9                | Filter connection supply voltage (only when light-colored BaseUnit is present)      | F0, F1           | Channel fault LED (red)                                 |
| l <sub>n</sub> + | Current input positive, channel n   | PWR              | Power LED (green)                                       |
| I <sub>n</sub> - | Current input negative, channel n   |                  |   |

Image 3-2 Wiring and block diagram for current measurement 2-wire and 4-wire connection (2-wire and 4-wire transducer)

Parameters/address space

## 4.1 Measurement types and measuring ranges

The following table shows the measurement types and the respective measuring range.

Table 4-1 Measurement types and measuring ranges

| Measurement type | Measuring range                           | Resolution            |
|------------------|---|-----------------------|
| Voltage          | ± 5 V                                     | 16 bits incl. sign    |
|                  | ± 10 V                                    | 16 bits incl. sign    |
|                  | 1 to 5 V                                  | 15 bits               |
|                  | 0 to 10 V                                 | 15 bits               |
| Current          | 0 to 20 mA (2-wire and 4-wire transducer) | 15 bits               |
|                  | 4 to 20 mA (2-wire and 4-wire transducer) | 15 bits               |
|                  | ± 20 mA (only with 4-wire transducer)     | 16 bit including sign |

You can find the tables of measuring ranges and overflow, overrange, etc. in the appendix Representation of analog values (Page 52) and the "Analog value processing" function manual.

#### Measuring range adjustment

See Measuring range adjustment (Page 21).

#### Scaling of measured values

See Scaling of measured values (Page 24).

#### 4.2 Parameters

#### Parameters of the AI 2xU/I 2-/4-wire HF

The following table lists the configurable parameters. The effective range of the configurable parameters depends on the type of configuration. The following configurations are possible:

- Central operation with an ET 200SP CPU
- Distributed operation on PROFINET IO in an ET 200SP system
- Distributed operation on PROFIBUS DP in an ET 200SP system

When assigning parameters in the user program, use the WRREC instruction to transfer the parameters to the module by means of data records; refer to the section Parameter assignment and structure of parameter data record (Page 42).

The following parameter settings are possible:

Table 4-2 Configurable parameters and their defaults (GSD file)

| Parameter                                  | Range of values                          | Default | Configura-<br>tion in RUN |                         | nfiguration soft-<br>P 7 (TIA Portal) |
|--|--|---------|---------------------------|-------------------------|---------------------------------------|
|  |  |         |                           | GSD file<br>PROFINET IO | GSD file<br>PROFIBUS DP               |
| Diagnostics:<br>No supply voltage<br>L+    | <ul><li>Disable</li><li>Enable</li></ul> | Disable | Yes                       | Channel                 | Channel                               |
| Diagnostics:<br>Short-circuit to<br>ground | <ul><li>Disable</li><li>Enable</li></ul> | Disable | Yes                       | Channel                 | Channel                               |
| Diagnostics:<br>Overflow                   | <ul><li>Disable</li><li>Enable</li></ul> | Disable | Yes                       | Channel                 | Channel                               |
| Diagnostics:<br>Underflow                  | <ul><li>Disable</li><li>Enable</li></ul> | Disable | Yes                       | Channel                 | Channel                               |
| Diagnostics:<br>Wire break                 | <ul><li>Disable</li><li>Enable</li></ul> | Disable | Yes                       | Channel                 | Channel                               |

#### 4.2 Parameters

| Parameter  | Range of values  | Default                            | Configura- | Scope with configuration software, e.g. STEP 7 (TIA Portal) |                         |
|--|--|------------------------------------|------------|---|-------------------------|
|  |  |                                    |            | GSD file<br>PROFINET IO                                     | GSD file<br>PROFIBUS DP |
| Measurement type/measuring range                   | <ul> <li>Deactivated</li> <li>Voltage         <ul> <li>±5 V</li> <li>±10 V</li> <li>1 V to 5 V</li> <li>0 V to 10 V</li> </ul> </li> <li>Current (4-wire transducer)         <ul> <li>0 to 20 mA</li> <li>±20 mA</li> </ul> </li> <li>Current (2-wire transducer)         <ul> <li>0 to 20 mA</li> <li>4 to 20 mA</li> <li>4 to 20 mA</li> </ul> </li> </ul> | Current (4-wire transducer) 420 mA | Yes        | Channel   | Channel                 |
| Smoothing  | <ul> <li>None</li> <li>2 times</li> <li>4 times</li> <li>8 times</li> <li>16 times</li> <li>32 times</li> </ul>  | None                               | Yes        | Channel   | Channel                 |
| Interference frequency suppression <sup>2</sup>    | <ul> <li>16.6 Hz (67.5 ms)</li> <li>50 Hz (22.5 ms)</li> <li>60 Hz (18.75 ms)</li> <li>300 Hz (10 ms)</li> <li>600 Hz (5 ms)</li> <li>1.2 kHz (2.5 ms)</li> <li>2.4 kHz (1.25 ms)</li> <li>4.8 kHz (0.625 ms)</li> </ul>   | 50 Hz (22.5 ms)                    | Yes        | Channel   | Channel                 |
| Measuring range adjustment <sup>1</sup>            | <ul><li>Disable</li><li>Enable</li></ul>   | Disable                            | Yes        | Channel   | -                       |
| Measuring range adjustment high limit <sup>1</sup> | Value within the nominal range of the measuring range in mV or μA  | 0                                  | Yes        | Channel   | -                       |
| Measuring range adjustment low limit 1             | Value within the nominal range of the measuring range in mV or μA  | 0                                  | Yes        | Channel   | -                       |
| Scaled high nominal range limit <sup>3</sup>       | REAL   | 20.0                               | Yes        | Channel   | -                       |
| Scaled low nominal range limit <sup>3</sup>        | REAL   | 4.0                                | Yes        | Channel   | -                       |

| Parameter   | Range of values   | Default                                | Configura-<br>tion in RUN | •                       | nfiguration soft-<br>P 7 (TIA Portal) |
|---|---|--|---------------------------|-------------------------|---------------------------------------|
|   |   |  |                           | GSD file<br>PROFINET IO | GSD file<br>PROFIBUS DP               |
| Hardware inter-<br>rupt high limit 1 <sup>1</sup> | <ul><li>Disable</li><li>Enable</li></ul>  | Disable                                | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt low limit 1 <sup>1</sup>  | Disable     Enable  | Disable                                | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt high limit 2 <sup>1</sup> | Disable     Enable  | Disable                                | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt low limit 2 <sup>1</sup>  | Disable     Enable  | Disable                                | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt high limit 1 <sup>1</sup> | <ul> <li>Value (INT)</li> <li>Value (REAL) <sup>3</sup></li> </ul>                            | • 27648<br>• 0.0 <sup>3</sup>          | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt low limit 1 <sup>1</sup>  | <ul> <li>Value (INT)</li> <li>Value (REAL) <sup>3</sup></li> </ul>                            | • 0<br>• 0.0 <sup>3</sup>              | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt high limit 2 <sup>1</sup> | <ul> <li>Value (INT)</li> <li>Value (REAL) <sup>3</sup></li> </ul>                            | • 27648<br>• 0.0 <sup>3</sup>          | Yes                       | Channel                 | -                                     |
| Hardware inter-<br>rupt low limit 2 <sup>1</sup>  | Value (INT) Value (REAL) <sup>3</sup>   | • 0<br>• 0.0 <sup>3</sup>              | Yes                       | Channel                 | -                                     |
| Potential group                                   | Use potential group of the<br>left module (module<br>plugged into a dark-colored<br>BaseUnit) | Use potential group of the left module | No                        | Module                  | Module                                |
|   | Enable new potential group<br>(module plugged into light-<br>colored BaseUnit)                |  |                           |                         |                                       |

- Due to the limited number of parameters at a maximum of 244 bytes per ET 200SP station with a PROFIBUS GSD configuration, the configuration options are restricted. If required, you can assign these parameters using data record 128 as described in the "GSD file PROFINET IO" column (see table above). The parameter length of the I/O module is 7 bytes.
- In normal operation, different interference frequency suppression settings can be configured for both channels. These cause different integration times for the analog-to-digital conversion. The module-internal time for updating the user data is now based on the longer integration time for both channels.
  In isochronous mode, both channels must be configured with the same interference frequency suppression of 4.8 kHz.
- <sup>3</sup> Only for configuration SCALE.

#### 4.3 Explanation of parameters

#### Note

#### Unused channels

Deactivate the unused inputs in the parameter assignment.

A deactivated input always returns the value  $7FFF_H$  or  $7F800000_H$  with measured value scaling.

#### Property of the module in isochronous mode

The permitted interference frequency suppression of both channels for isochronous mode of the modules is 4.8 kHz (0.625 ms).

Note that no instantaneous value for the time Ti is returned in isochronous mode. The analog module Al 2xU/I 2-/4-wire HF returns a mean value for the range of 0.625 ms starting at Ti.

## 4.3 Explanation of parameters

#### Diagnostics: No supply voltage L+

Enabling of the diagnostics for no or insufficient supply voltage L+.

#### Diagnostics: Short-circuit to ground

Enabling of the diagnostics if a short-circuit of the actuator supply to ground occurs. A short-circuit is also detected in the range of 1 to 5 V if the input signal is short-circuited or the input is not connected.

The short-circuit and underflow diagnostics can be activated simultaneously. If both diagnostics events occur simultaneously, the short-circuit diagnostics is output.

#### **Diagnostics: Overflow**

Enabling of the diagnostics when the measured value exceeds the overrange.

#### **Diagnostics: Underflow**

Enabling of the diagnostics when the measured value falls below the underrange.

#### Diagnostics: Wire break

Enable the diagnostics if the module has no current flow or has too little current for the measurement in the range of 4 to 20 mA.

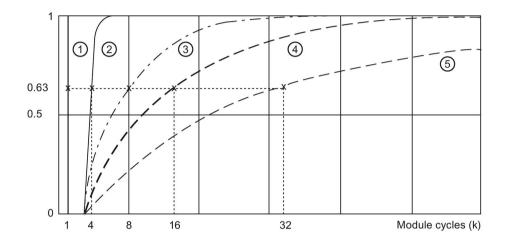
The wire break and underflow diagnostics can be activated simultaneously. If both diagnostics events occur simultaneously, the wire break diagnostics is output.

#### **Smoothing**

The individual measured values are smoothed by filtering. The smoothing can be set in 5 levels.

Smoothing time = number of module cycles (k) x cycle time of the module.

The following figure shows how many module cycles it takes for the smoothed analog value to approach 100%, depending on the configured smoothing. This applies to every signal change at the analog input.



- 1 No smoothing (k = 1)
- Weak (k = 4)
- 3 Medium (k = 8)
- 4 Strong (k = 16)
- 5 Very strong (k = 32)

Image 4-1 Smoothing AI 2×U/I 2-/4-wire HF

#### Interference frequency suppression

Suppresses the interference affecting analog input modules that is caused by the frequency of the AC voltage network used.

The frequency of the AC voltage network can negatively affect the measured value, in particular when measuring in the low voltage range and with thermocouples. With this parameter, the user specifies the line frequency that is predominant in the plant.

#### Measuring range adjustment

The measuring range adjustment is a limited section of a measuring range supported by the analog input module. It is available for current and voltage measurements.

A limited measuring range in S7 format is shown, which is defined by the high and low limits of the measuring range adjustment.

#### 4.3 Explanation of parameters

#### Scaling of measured values

With measured value scaling, the user data of an analog input module is displayed as REAL (32-bit floating point) instead of S7 format.

The representation of the measuring range is defined by the scaled high and low limits of nominal range limit (as REAL).

The measured value scaling can be combined with the measuring range adjustment. In this case, the measuring range is adjusted first and then the representation of the measuring range is scaled.

#### BaseUnit with incoming supply voltage

Specifies that a light-colored BaseUnit with incoming supply voltage is located on this slot (see ET 200SP distributed I/O system

(http://support.automation.siemens.com/WW/view/en/58649293) system manual).

#### Potential group

A potential group consists of a group of directly adjacent I/O modules within an ET 200SP station, which are supplied via a common supply voltage.

A potential group begins with a light-colored BaseUnit through which the required voltage is supplied for all modules of the potential group. The light-colored BaseUnit interrupts the three self-assembling voltage buses P1, P2 and AUX to the left neighbor.

All additional I/O modules of this potential group are plugged into dark-colored BaseUnits. You take the potential of the self-assembling voltage buses P1, P2 and AUX from the left neighbor.

A potential group ends with the dark-colored BaseUnit, which follows a light-colored BaseUnit or server module in the station configuration.

#### See also

You can find additional information in the system manual ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293).

## 4.4 Measuring range adjustment

#### Introduction

The measuring range adjustment is available for current and voltage measuring ranges.

The measuring range adjustment (base measuring range) is valid for the following ranges:

- Nominal range
- Underrange (of the measuring range adjustment)
- Overrange (of the measuring range adjustment)

#### Note

Live zero measuring ranges are not supported.

#### **Function**

The measuring range adjustment is a limited section of a measuring range supported by the module.

It allows you to increase the resolution for a configurable part of the measuring range in S7 format.

- The function is enabled with the "Measuring range adjustment" parameter
- The "Measuring range adjustment high limit" parameter sets the high limit of the measuring range in mV or μA.
- The "Measuring range adjustment low limit" parameter sets the low limit of the measuring range in mV or μA.

#### Note

The "Measuring range adjustment" function can be used in combination with the "Measured value scaling" function. See also Scaling of measured values (Page 24).

#### Note

When the "Measuring range adjustment high limit" and "Measuring range adjustment low limit" parameters are too close together, resolution may be lost, which means it may no longer be possible to show every value.

#### 4.4 Measuring range adjustment

#### Rules

- The limits of the measuring range adjustment must be selected within the nominal range of the base measuring range. They are specified in integers.
- The measuring range adjustment is resolved depending on the base measuring range from 0<sub>H</sub> to 6C00<sub>H</sub> or 9400<sub>H</sub> to 6C00<sub>H</sub>.
- Underranges/overranges apply in accordance with the S7 format and the base measuring range.

Special consideration: Negative values are not possible for "Current (2-wire transducer) 0..20 mA". With a measuring range adjustment, an underrange is offered when possible and cut off at 0 mA. If the underrange limit (ED00<sub>H</sub>) is > 0 mA, QI = 0 and the analog value  $8000_H$  are output when it is violated.

#### Example

The following values result, for example:

Table 4-3 Example of measuring range adjustment

| Measuring range adjustment            | Measuring range resolution |                          |  |
|---------------------------------------|----------------------------|--------------------------|--|
|                                       | Bipolar                    | Unipolar                 |  |
| Base measuring range                  | ±10 V                      | 0 V to 10 V              |  |
| Adjusted measuring range              | +2 V to +5 V               | +2 V to +5 V             |  |
| Measuring range adjustment high limit | 5000 mV<br>(S7: +27648)    | 5000 mV<br>(\$7: +27648) |  |
| Measuring range adjustment low limit  | 2000 mV<br>(S7: -27648)    | 2000 mV<br>(S7: 0)       |  |

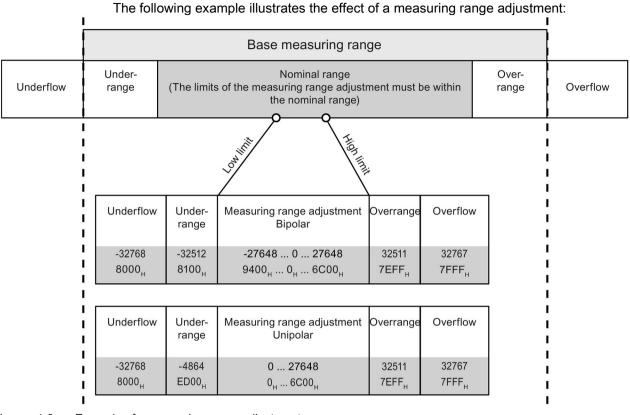


Image 4-2 Example of a measuring range adjustment

#### Configuration

The following figure shows an example of a configuration:

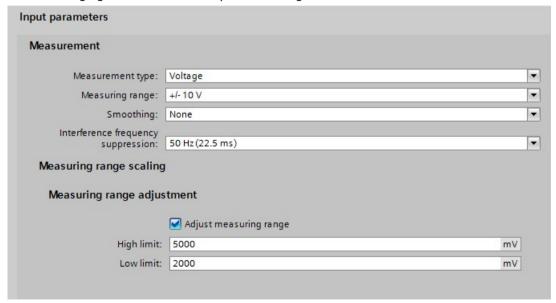


Image 4-3 Example of a configuration

In the configuration example, a measuring range adjustment of 2000 mV to 5000 mV is displayed.

## 4.5 Scaling of measured values

#### Introduction

The measured value scaling can be combined with the measuring range adjustment. In this case, the measuring range is adjusted first and then the representation of the measuring range is scaled.

#### **Function**

With measured value scaling, the user data of an AI 2xU/I 2-/4-wire HF module is displayed as REAL (32-bit floating point) instead of S7 format.

The representation of the measuring range is defined by the following parameters:

- The "Scaled high nominal range limit" parameter sets the desired display value (in REAL) for the high nominal range limit of the measuring range.
- The "Scaled low nominal range limit" parameter sets the desired display value (in REAL) for the low nominal range limit of the measuring range.

#### Note

With measured value scaling, the substitute value is minus infinity for underflow (FF800000H) and plus infinity for overflow (7F800000H).

#### Note

#### Effects of inversion

It is possible to set the "Scaled high nominal range limit" parameter lower than the "Scaled low nominal range limit" parameter, whereby the representation of the measuring range will be inverted compared to the terminal value (V, mA).

Overflow/underflow and hardware interrupts are always based on representation in REAL. A terminal value of > 11.76 V triggered an underflow for an inverted measured value scaling. Hardware interrupts react similarly.

#### Note

When the Parameter "Scaled high nominal range limit" and "Scaled low nominal range limit" parameters are too close together, resolution may be lost, which means it may no longer be possible to show every value.

#### **Example**

The following values result, for example:

Table 4-4 Example of measured value scaling

|                            | Low nominal range limit | High nominal range limit |
|----------------------------|-------------------------|--------------------------|
| Base measuring range       | -10 V                   | +10 V                    |
| S7 format                  | -27648                  | +27648                   |
| Scaling of measured values | 1.00                    | 7.00                     |

As shown in the table, -10 V corresponds to 1.00 and +10 V corresponds to 7.00.

#### Combination with measuring range adjustment

If the measuring range adjustment is enabled in addition to measured value scaling, first the measuring range is scaled and then the representation of the measuring range. The table below shows an example of the combination of measured value scaling and measuring range adjustment.

Table 4-5 Example for a combination of measured value scaling and measuring range adjustment

|                            | Low nominal range limit | High nominal range limit |
|----------------------------|-------------------------|--------------------------|
| Measuring range adjustment | -4000 mV                | 8000 mV                  |
| S7 format                  | -27648                  | +27648                   |
| Scaling of measured values | 1.00                    | 7.00                     |

As shown in the table, -4 V corresponds to 1.00 and +8 V corresponds to 7.00.

## Configuration

The following figures show examples of a configuration in STEP 7:

#### Configuration of measured value scaling



Image 4-4 Configuration of measured value scaling

#### 4.5 Scaling of measured values

#### Configuration with measuring range adjustment and measured value scaling

In the configuration example, a measuring range adjustment of -4000 mV to 8000 mV is displayed and additionally converted to a scaled high and low nominal range limit of 1.00 to 7.00.

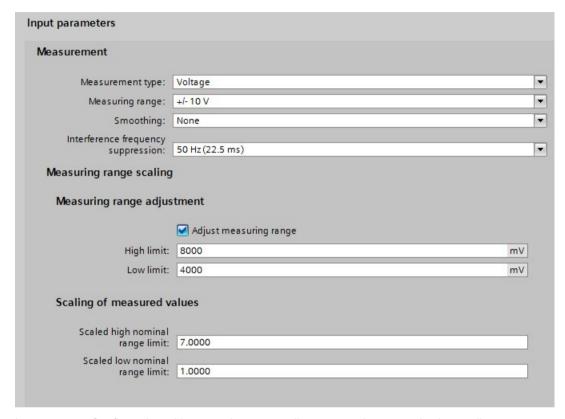


Image 4-5 Configuration with measuring range adjustment and measured value scaling

## 4.6 Address space

The module can be configured differently in STEP 7; see following table. Depending on the configuration, additional/different addresses are assigned in the process image of the inputs.

#### Configuration options of AI 2xU/I 2-/4-wire HF

You can configure the module with STEP 7 (TIA Portal) or with a GSD file. If you configure the module by means of a GSD file, the configurations are available under various short designations/module names; see the table below. The following configurations are possible:

Table 4-6 Configuration options with GSD file

| Configuration  | Short designation/module name in the GSD file | Configuration software, e.g. with STEP 7 (TIA Portal)     |                         |                         |
|--|---|---|-------------------------|-------------------------|
| name   |   | Integrated in the hardware catalog STEP 7, as of V13, SP1 | GSD file<br>PROFINET IO | GSD file<br>PROFIBUS DP |
| 1 x 2-channel without value status   | AI 2xU/I 2-, 4-wire HF<br>V1.0                | Х   | Х                       | Х                       |
| 1 x 2-channel with value status  | AI 2xU/I 2-, 4-wire HF<br>V1.0, QI            | Х   | Х                       |                         |
| 1 x 2-channel without value status   | AI 2xU/I 2-, 4-wire HF<br>V2.0                |   | Х                       | Х                       |
| 1 x 2-channel with value status  | AI 2xU/I 2-, 4-wire HF<br>V2.0, QI            |   | Х                       |                         |
| 1 x 2-channel with value status<br>for module-internal Shared Input<br>with up to 4 submodules | AI 2xU/I 2-, 4-wire HF<br>V2.0, MSI           |   | Х                       |                         |
| 1 x 2-channel with value status and measured value scaling                                     | AI 2xU/I 2-, 4-wire HF<br>V2.0, SCALE         |   | Х                       |                         |

#### Value status (Quality Information, QI)

The value status is always activated for the following module names:

- Al 2xU/I 2-, 4-wire HF, QI,
- Al 2xU/I 2-, 4-wire HF, MSI
- Al 2xU/I 2-, 4-wire HF, SCALE

An additional bit is assigned to each channel for the value status. The value status bit indicates whether the read in analog value is valid. (0 = value is incorrect).

## Evaluating the value status

If you enable the value status for the analog module, an additional byte is occupied in the input address space. Bits 1 and 0 in this byte are assigned to a channel. They provide information about the validity of the analog value.

Bit = 1: No fault is present on the channel.

Bit = 0: The wiring, the value created on the channel, etc. is incorrect.

#### Address space for configuration as 1 x 2-channel Al 2×U/I 2-/4-wire HF, QI

The following figure shows the assignment of the address space for the AI 2xU/I 2-/4-wire HF, QI with value status (Quality Information (QI)). The addresses for the value status are only available if the value status is enabled.

Assignment in the process image input (PII)

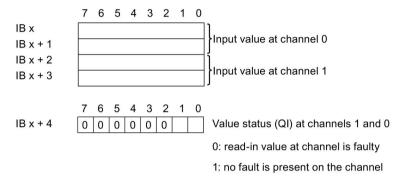


Image 4-6 Address space of the analog input module AI 2xU/I 2-/4-wire HF, QI with value status

## Address space for configuration as 1 x 2-channel AI 2×U/I 2-/4-wire HF MSI

For the configuration as a 1 x 2-channel module (module-internal shared input, MSI), channels 0 and 1 of module are copied to up to four submodules. Channels 0 and 1 are then available with identical input values in various submodules. These submodules can be assigned to up to four IO controllers when the module is used in a shared device. Each IO controller has read access to the same channels.

The number of usable submodules is dependent on the interface module used. Please observe the information in the manual for the particular interface module.

#### Value status (Quality Information, QI)

The meaning of the value status depends on the submodule on which it occurs.

For the 1st submodule (=basic submodule), the value status 0 indicates that the value is incorrect.

For the 2nd to 4th submodule (=MSI submodule), the value status 0 indicates that the value is incorrect or the basic submodule has not yet been configured (not ready).

The following figure shows the assignment of the address space with submodules 1 and 2.

Assignment in the process image of the inputs (PII) Input value 1st submodule 7 6 5 4 3 2 1 0 (Basic submodule): IB a Channel 0 IB (=a+1) IB (=a+2) Channel 1 IB (=a+3) 6 5 4 3 2 1 0 IB (=a+4) 0 0 0 0 0 0 Channels 0 and 1 (value status QI0 and QI1) Input value 2nd submodule 7 6 5 4 3 2 1 0 (MSI submodule): IB b Channel 0 IB (=b+1) IB (=b+2) Channel 1 IB (=b+3)7 6 5 4 3 2 1 0

0 = Value read at the channel is faulty

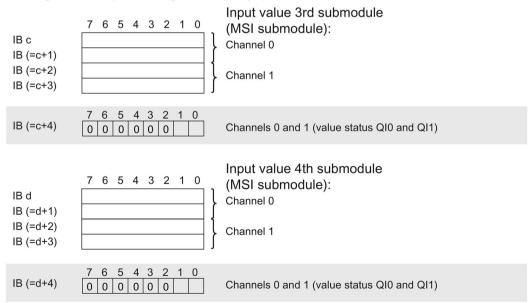
Image 4-7 Address space for configuration as 1x 2-channel Al 2×U/I 2-/4-wire HF MSI with value status

Channels 0 and 1 (value status QI0 and QI1)

The figure below shows the assignment of the address space with submodules 3 and 4.

Assignment in the process image of the inputs (PII)

0 0 0 0 0 0 0



0 = Value read at the channel is faulty

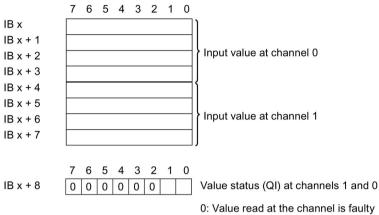
Image 4-8 Address space for configuration as 1x 2-channel Al 2×U/I 2-/4-wire HF MSI with value status

IB (=b+4)

#### Address space for configuration as 1 x 2-channel Al 2×U/I 2-/4-wire HF SCALE

The following figure shows the assignment of the address space for the AI 2xU/I 2-/4-wire HF, SCALE with value status (Quality Information (QI)). The value status cannot be deselected for this configuration.

Assignment in the process image of the inputs (PII)



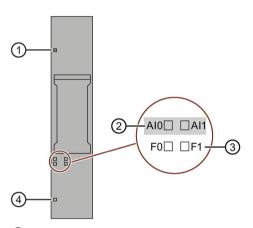
0: Value read at the channel is faulty1: No fault is present on the channel.

Image 4-9 Address space for configuration as 1 x 2-channel Al 2×U/I 2-/4-wire HF, SCALE with value status

## 5.1 Status and error displays

## LED displays

The following figure shows you the LED display of the AI 2xU/I 2-/4-wire HF.



- ① DIAG (green/red)
- ② Channel status (green)
- 3 Channel error (red)
- 4 PWR (green)

Image 5-1 LED display

#### 5.1 Status and error displays

## Meaning of the LED displays

The following tables contain the meaning of the status and error displays. Remedies for diagnostics alarms can be found in section Diagnostics alarms (Page 35).

Table 5- 1 Error display DIAG LED

| DIAG LED | Meaning  |
|----------|--|
|          | Backplane bus supply of the ET 200SP not OK          |
| Off      |  |
| 渋        | Module parameters not assigned                       |
| Flashes  |  |
|          | Module parameters assigned and no module diagnostics |
| On       |  |
| 崇        | Module parameters assigned and module diagnostics    |
| Flashes  |  |

Table 5-2 Status and error display LED channel status / channel error

| LEDs           |               | Meaning                                      |
|----------------|---------------|--|
| Channel status | Channel error |  |
|                |               | Channel deactivated or load voltage missing  |
| Off            | Off           |  |
|                |               | Channel activated and no channel diagnostics |
| On             | Off           |  |
|                |               | Channel activated and channel diagnostics    |
| Off            | On            |  |
|                |               | Not permitted (error)                        |
| On             | On            |  |

Table 5-3 PWR LED status display

| PWR LED | Meaning              |
|---------|----------------------|
| Off     | Load voltage missing |
| OII     | Load voltage present |
| On      |                      |

## 5.2 Interrupts

The analog input module AI 2×U/I 2-/4-wire HF supports hardware and diagnostic interrupts.

#### **Diagnostics interrupts**

The module generates a diagnostic interrupt at the following events:

- Short-circuit (current: sensor supply; voltage: 1 to 5 V, encoder supply)
- Wire break (current: 4 to 20 mA)
- High limit violated
- · Low limit violated
- Error
- Parameter assignment error
- Hardware interrupt lost
- Supply voltage missing
- Channel temporarily unavailable

#### Hardware interrupts

The module generates a hardware interrupt at the following events:

- Violation of low limit 1
- Violation of high limit 1
- Violation of low limit 2
- Violation of high limit 2

#### S7-1500

Detailed information on the event is available in the STEP 7 online help.

The block interface is represented here with optimized block access, which is set in the TIA Portal by default.

| Name      | Data type | Comment  |
|-----------|-----------|--|
| LADDR     | HW_IO     | Hardware identifier of the module triggering the interrupt |
| USI       | WORD      | USI (High/Low)   |
| IChannel  | USInt     | Channel that triggered the hardware interrupt              |
| EventType | Byte      | Error event  |

#### S7-300/400 or a different CPU

You can obtain detailed information on the event in the hardware interrupt organization block with the "RALARM" (read additional interrupt information) instruction and in the STEP 7 online help.

The module channel that triggered the hardware interrupt is entered in the start information of the organization block. The following figure shows the assignment to the bits of double word 8 in local data.

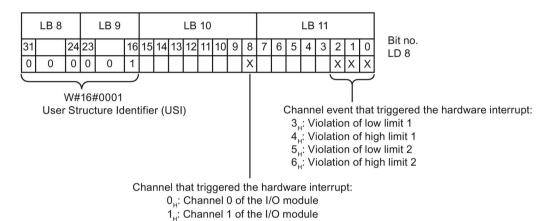


Image 5-2 OB start information

## Structure of the additional interrupt information

Table 5-4 Structure of the additional interrupt information

| Data        | block name                      | Content            | Comment  | Bytes |
|-------------|---------------------------------|--------------------|--|-------|
| USI<br>(Use | r Structure Identifier)         | W#16#0001          | Additional interrupt information for hardware interrupts of the I/O module | 2     |
| Char        | nnel that triggered the hardwar | e interrupt.       |  |       |
|             | Channel                         | B#16#00 to B#16#01 | Channel 0 and 1 of the I/O module  | 1     |
| Even        | t that triggered the hardware i | nterrupt.          |  |       |
|             | Error event                     | B#16#03            | Violation of low limit 1   | 1     |
|             |                                 | B#16#04            | Violation of high limit 1  |       |
|             |                                 | B#16#05            | Violation of low limit 2   |       |
|             |                                 | B#16#06            | Violation of high limit 2  |       |

## 5.3 Diagnostics alarms

A diagnostics alarm is generated and the DIAG-LED flashes on the module for each diagnostics event. You can read out the diagnostics alarms, for example, in the diagnostics buffer of the CPU. You can evaluate the error codes with the user program.

Table 5-5 Diagnostics alarms, their meaning and corrective measures

| Diagnostics alarm               | Error code      | Meaning   | Solution  |  |
|---------------------------------|-----------------|---|---|--|
| Short-circuit (encoder supply)  | 1н              | Short-circuit encoder supply to ground  | Correct interplay between module and encoder  |  |
| Short-circuit (1 to 5 V)        | 1н              | Short-circuit of input signal   | Correct interplay between module and encoder  |  |
|                                 |                 | Open input  | Connect input   |  |
| Wire break (current 4 to 20 mA) | 6н              | Impedance of encoder circuit too high   | Use a different encoder type or modify the wiring, e.g. use cables with larger cross-section  |  |
|                                 |                 | Wire break between the module and sensor  | Connect the cable   |  |
|                                 |                 | Channel not connected (open)  | Disable diagnostics   |  |
|                                 |                 |   | Connect the encoder contacts  |  |
| High limit violated             | 7 <sub>H</sub>  | Value is above the overrange.   | Correct interplay between module and encoder  |  |
| Low limit violated              | 8н              | Value is below the underrange.  | Correct interplay between module and encoder  |  |
| Error                           | 9 <sub>H</sub>  | Internal module error has occurred (diagnostics alarm on channel 0 applies for the entire module).                    | Replace module  |  |
| Parameter assignment error      | 10 <sub>H</sub> | The module cannot evaluate parameters for the channel:  | Correct the parameter assignment<br>(wire break diagnostics set only with   |  |
|                                 |                 | Incorrect parameter assignment.   | the permitted measuring ranges).  |  |
| Supply voltage missing          | 11н             | Missing or insufficient supply voltage L+   | Check supply voltage L+ on the<br>BaseUnit  |  |
|                                 |                 |   | Check BaseUnit type   |  |
| Hardware interrupt lost         | 16 <sub>H</sub> | Error is reported when a hardware interrupt (high/low limit) could not be reported.                                   | <ul> <li>Limits might be assigned twice.</li> <li>If necessary, reduce the bus cycle.</li> <li>If necessary, use higher SFU.</li> </ul> |  |
| Channel temporarily unavailable | 1F <sub>H</sub> | Firmware update is currently in progress or has been canceled. The module does not read process values in this state. | Wait for firmware update     Restart the firmware update  |  |
|                                 |                 | Switch to user calibration  |   |  |

**Technical specifications** 

# 6

## Technical specifications of the Al 2×U/I 2-/4-wire HF

|  | 6ES7134-6HB00-0CA1                             |  |
|--|--|--|
| General information  |  |  |
| Product type designation                                     | ET 200SP, AI 2xU/I 2/4-wire High Feature, PU 1 |  |
| Firmware version   | V2.0   |  |
| FW update possible   | Yes  |  |
| Usable BaseUnits   | BU type A0, A1                                 |  |
| Color code for module-specific color identification label    | CC03   |  |
| Product function   |  |  |
| I&M data   | Yes; I&M0 to I&M3                              |  |
| Scalable measuring range                                     | No   |  |
| Engineering with   |  |  |
| STEP 7 TIA Portal can be configured/integrated as of version | V13  |  |
| STEP 7 can be configured/integrated as of version            | V5.5 / -                                       |  |
| PCS 7 can be configured/integrated as of version             | V8.1 SP1                                       |  |
| PROFIBUS as of GSD version/GSD revision                      | GSD revision 5                                 |  |
| PROFINET as of GSD version/GSD revision                      | GSDML V2.3                                     |  |
| Operating mode   |  |  |
| Oversampling   | No   |  |
| MSI  | Yes  |  |
| CiR Configuration in RUN                                     |  |  |
| Configuration in RUN possible                                | Yes  |  |
| Calibration in RUN possible                                  | Yes  |  |
| Supply voltage   |  |  |
| Rated value (DC)   | 24 V   |  |
| Valid range, low limit (DC)                                  | 19.2 V   |  |
| Valid range, high limit (DC)                                 | 28.8 V   |  |
| Polarity reversal protection                                 | Yes  |  |
| Input current  |  |  |
| Current consumption (rated value)                            | 39 mA; without sensor supply                   |  |

|   | 6ES7134-6HB00-0CA1  |
|---|---|
| Encoder supply  | <b>52</b> 01101 011200 00111                                      |
| 24 V encoder supply   |   |
| 24 V  | Yes   |
| Short-circuit protection  | Yes   |
| Output current, max.  | 20 mA; max. 50 mA per channel for a duration <                    |
| •   | 10 s (two-wire)   |
| Additional 24 V encoder supply  |   |
| Short-circuit protection  | Yes; channel-based  |
| Output current, max.  | 100 mA; max. 150 mA per channel for a duration < 10 s (four-wire) |
| Power loss  |   |
| Power loss, typ.  | 0.95 W; without sensor supply                                     |
| Address area  |   |
| Address space per module  |   |
| Address space per module, max.  | 4 bytes; + 1 byte for QI information                              |
| Analog inputs   |   |
| Number of analog inputs   | 2; Differential inputs  |
| Maximum permissible input voltage for voltage input (destruction limit) | 30 V  |
| Permissible input current for current input (destruction limit), max.   | 50 mA   |
| Input ranges (rated values), voltages                                   |   |
| 0 to +10 V  | Yes; 15 bits  |
| Input resistance (0 to 10 V)  | 75 kΩ   |
| 1 V to 5 V  | Yes; 15 bits  |
| Input resistance (1 V to 5 V)   | 75 kΩ   |
| -10 V to +10 V  | Yes; 16 bits incl. sign   |
| Input resistance (-10 V to +10 V)                                       | 75 kΩ   |
| -5 V to +5 V  | Yes; 16 bits incl. sign   |
| Input resistance (-5 V to +5 V)   | 75 kΩ   |
| Input ranges (rated values), currents                                   |   |
| 0 mA to 20 mA   | Yes; 15 bits  |
| Input resistance (0 to 20 mA)   | 130 Ω   |
| -20 mA to +20 mA  | Yes; 16 bits incl. sign   |
| Input resistance (-20 mA to +20 mA)                                     | 130 Ω   |
| 4 mA to 20 mA   | Yes; 15 bits  |
| Input resistance (4 mA to 20 mA)  | 130 Ω   |
| Cable length  |   |
| Shielded, max.  | 1000 m; 200 m for voltage measurement                             |

| -   |  |
|---|--|
|   | 6ES7134-6HB00-0CA1                                 |
| Formation of analog values for the inputs   |  |
| Measuring principle   | Sigma Delta  |
| Integration and conversion time/resolution per channel  |  |
| Resolution with overrange (bit including sign), max.  | 16 bits  |
| Integration time configurable   | Yes  |
| Interference voltage suppression for interference frequency f1 in Hz                            | 16.6 / 50 / 60 / 300 / 600 / 1 200 / 2 400 / 4 800 |
| Basic execution time of the module (all channels enabled)                                       | 1 ms   |
| Measured value smoothing  |  |
| Number of levels  | 6; none; 2/4/8/16/32 times                         |
| Configurable  | Yes  |
| Encoders  |  |
| Connection of the signal transmitters   |  |
| For voltage measurement   | Yes  |
| For current measurement as 2-wire transducer  | Yes  |
| Load of 2-wire transducer, max.   | 650 Ω  |
| For current measurement as 4-wire transducer  | Yes  |
| Errors/accuracies   |  |
| Linearity error (in relation to input range), (+/-)   | 0.01%  |
| Temperature error (in relation to input range), (+/-)   | 0.003%/K   |
| Crosstalk between inputs, min.  | -50 dB   |
| Repeat accuracy in settled state at 25 °C (in relation to input range), (+/-)                   | 0.01%  |
| Operational limit in the entire temperature range   |  |
| Voltage in relation to input range, (+/-)   | 0.1%   |
| Current in relation to input range, (+/-)   | 0.1%   |
| Basic error limit (operational limit at 25 °C)  |  |
| Voltage in relation to input range, (+/-)   | ± 0.05%; 0.1% with SFU 4.8 kHz                     |
| Current in relation to input range, (+/-)   | ± 0.05%; 0.1% with SFU 4.8 kHz                     |
| Interference voltage suppression for $f = n \times (f1 +/-1\%)$ , $f1 = interference$ frequency |  |
| Common mode voltage, max.   | 35 V   |
| Common mode interference, min.  | 90 dB  |
| Isochronous mode  |  |
| Isochronous mode (application synchronized up to terminal)                                      | Yes  |
| Filtering and processing time (TCI), min.   | 800 μs   |
| Bus cycle time (TDP), min.  | 1 ms   |
| Jitter, max.  | 5 μs   |

|  | 6ES7134-6HB00-0CA1   |
|--|--|
| Interrupts/diagnostics/status information                  |  |
| Interrupts   |  |
| Diagnostics interrupt                                      | Yes  |
| Limit interrupt  | Yes; two high limits and two low limits each   |
| Diagnostics alarms   |  |
| Diagnostics  | Yes  |
| Monitoring of the supply voltage                           | Yes  |
| Wire break   | Yes, measuring range 4 to 20 mA only   |
| Short-circuit  | Yes; for 1 to 5 V, and for current measuring ranges for short-circuit in sensor supply |
| Group error  | Yes  |
| Overflow/underflow   | Yes  |
| Diagnostics indicator LED                                  |  |
| Monitoring of the supply voltage (PWR LED)                 | Yes; green PWR LED   |
| Channel status display                                     | Yes; green LED   |
| For channel diagnostics                                    | Yes; red LED   |
| For module diagnostics                                     | Yes; green/red DIAG LED  |
| Electrical isolation                                       |  |
| Electrical isolation of channels                           |  |
| Between the channels                                       | Yes  |
| Between the channels and backplane bus                     | Yes  |
| Between the channels and voltage supply of the electronics | Yes  |
| Permitted potential difference                             |  |
| Between different circuits                                 | 75 V DC / 60 V AC (basic isolation)  |
| Between the inputs (UCM)                                   | 75 V DC/60 V AC  |
| Isolation  |  |
| Isolation tested with                                      | 707 V DC (type test)   |
| Dimensions   |  |
| Width  | 15 mm  |
| Weights  |  |
| Weight, approx.  | 32 g   |

### **Dimension drawing**

See manual ET 200SP BaseUnits

(http://support.automation.siemens.com/WW/view/en/59753521)

# Parameter data record



# A.1 Dependencies when configuring with GSD file

When configuring the module with a GSD file, remember that the settings of some parameters are dependent on each other.

### Configuring with a PROFINET GSD file

The table lists the properties and their dependencies on the measurement type and measuring range for PROFINET.

| Measurement                         | Measuring        |           | Hardware |            |                         |                                 |            |
|-------------------------------------|------------------|-----------|----------|------------|-------------------------|---------------------------------|------------|
| type                                | range            | Underflow | Overflow | Wire break | Short-circuit to ground | Missing<br>supply<br>voltage L+ | interrupts |
| Deactivated                         | *                | *         | *        | *          | *                       | *                               | *          |
| Voltage                             | ±5 V             | x         | х        | _          | x 1                     | х                               | x          |
|                                     | ±10 V            | x         | х        | _          | x 1                     | х                               | x          |
|                                     | 1 V to 5 V       | x         | x        | _          | x                       | х                               | x          |
|                                     | 0 V to 10 V      | x         | х        | _          | x 1                     | х                               | x          |
| Current<br>(4-wire trans-           | 0 mA to<br>20 mA | x         | x        | -          | x                       | x                               | x          |
| ducer)                              | 4 mA to<br>20 mA | х         | x        | x          | х                       | х                               | x          |
|                                     | ±20 mA           | х         | х        | -          | х                       | х                               | х          |
| Current<br>(2-wire trans-<br>ducer) | 0 mA to<br>20 mA | x 12      | х        | -          | х                       | х                               | х          |
|                                     | 4 mA to<br>20 mA | х         | x        | x          | х                       | x                               | x          |

x = property is allowed, - = property is **not allowed**, \* = property is not relevant

only possible as of firmware V2.0

<sup>&</sup>lt;sup>2</sup> The diagnostics Underflow can always be enabled for "Current (2-wire transducer) 0..20 mA", but it is only reported when a complete underflow range is created by the measuring range adjustment.

## Configuring with a PROFIBUS GSD file

The table lists the properties and their dependencies on the measurement type and measuring range for PROFIBUS.

Table A- 1 Dependencies of the measurement type and measuring range PB

| Measure-                          | Measuring        |           | Hardware |            |                    |                            |   |            |
|-----------------------------------|------------------|-----------|----------|------------|--------------------|----------------------------|---|------------|
| ment type                         | range            | Underflow | Overflow | Wire break | Load<br>voltage L+ | Short-circuit<br>to ground | Smoothing<br>/ interfer-<br>ence fre-<br>quency<br>suppres-<br>sion | interrupts |
| Deactivated                       | *                | *         | *        | *          | *                  | *                          | *   | *          |
| Voltage                           | ±5 V             | х         | х        | _          | х                  | x 1                        | х   | ı          |
|                                   | ±10 V            | х         | х        | _          | х                  | x 1                        | х   | _          |
|                                   | 1 V to 5 V       | х         | x        | _          | х                  | x                          | х   | -          |
|                                   | 0 V to 10 V      | х         | x        | _          | х                  | x 1                        | х   | _          |
| Current<br>(4-wire                | 0 mA to<br>20 mA | х         | x        | _          | х                  | x                          | x   | -          |
| transducer)                       | 4 mA to<br>20 mA | x         | ×        | x          | х                  | ×                          | x   | -          |
|                                   | ±20 mA           | х         | х        | -          | х                  | х                          | х   | -          |
| Current<br>(2-wire<br>transducer) | 0 mA to<br>20 mA | _         | х        | -          | х                  | х                          | x   | _          |
|                                   | 4 mA to<br>20 mA | x         | x        | x          | х                  | x                          | х   | _          |

x = property is allowed, - = property is **not allowed**, \* = property is not relevant

only possible as of firmware V2.0

### A.2 Parameter assignment and structure of parameter data record

The data records of the module have an identical structure, regardless of whether you configure the module with PROFIBUS DP or PROFINET IO.

#### Parameter assignment in the user program

You can reassign the module parameters in RUN. For example, the measuring range of selected channels can be changed in RUN without having an effect on the other channels.

#### Changing parameters in RUN

The "WRREC" instruction is used to transfer the parameters to the module using data record 128. The parameters set in STEP 7 are not changed in the CPU, which means that the parameters set in STEP 7 will be valid again after a restart.

#### Note

#### Changing parameters in RUN

A parameter data record that has content different from the startup parameter assignment results in a brief exit from clocked measuring mode and renewed synchronization with the fieldbus cycle. The slowest channel provides the "internal" measuring cycle.

#### Note

Changing parameter settings in runtime can cause the process values to freeze for the duration of the parameter assignment for the module.

#### **Output parameter STATUS**

If errors occur when transferring parameters with the "WRREC" instruction, the module continues operation with the previous parameter assignment. However, the STATUS output parameter contains a corresponding error code.

You will find a description of the "WRREC" instruction and the error codes in the STEP 7 online help.

#### Structure of data record 128

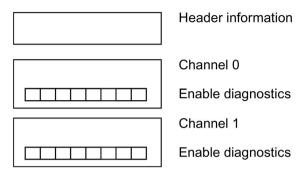


Image A-1 Structure of data record 128

### Header information (V1.0)

The figure below shows the structure of the header information (V1.0).

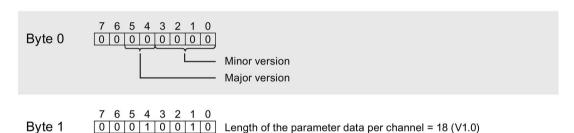


Image A-2 Header information (V1.0)

#### Header information (V2.0)

The figure below shows the structure of the header information (V2.0).

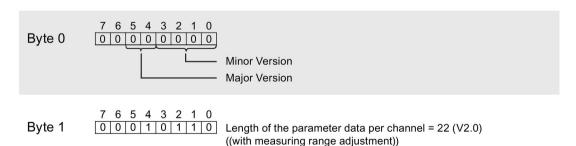
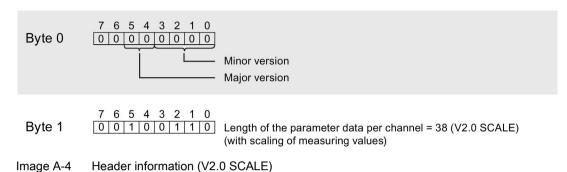


Image A-3 Header information (V2.0)

A.2 Parameter assignment and structure of parameter data record

#### Header information (V2.0 SCALE)

The figure below shows the structure of the header information.

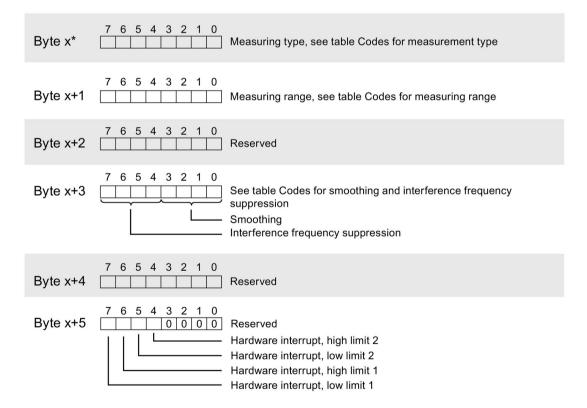


#### Parameter (V1.0)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 18); channel number is 0 or 1



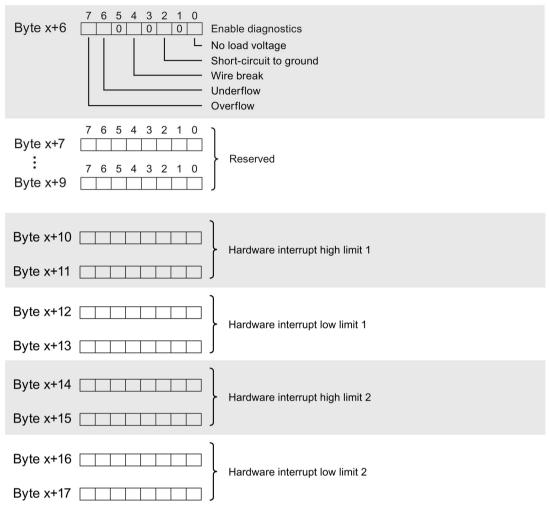


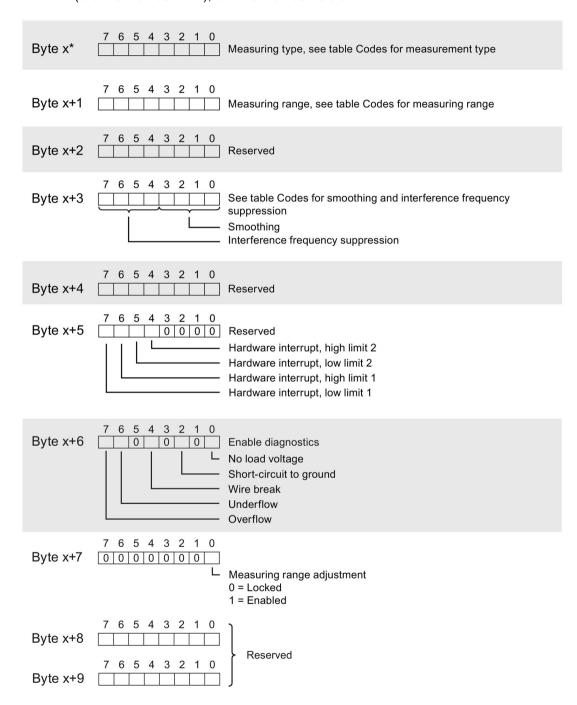
Image A-5 Structure of byte x to x+17 for channel 0 and 1

#### Parameter (V2.0)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 22); channel number is 0 or 1



| Byte x+10           | }                | Hardware interrupt high limit 1       |
|---------------------|------------------|---------------------------------------|
| Byte x+12           | }                | Hardware interrupt low limit 1        |
| Byte x+14 Byte x+15 | }                | Hardware interrupt high limit 2       |
| Byte x+16           | $\left. \right $ | Hardware interrupt low limit 2        |
| Byte x+18           | }                | Measuring range adjustment high limit |
| Byte x+20           | }                | Measuring range adjustment low limit  |

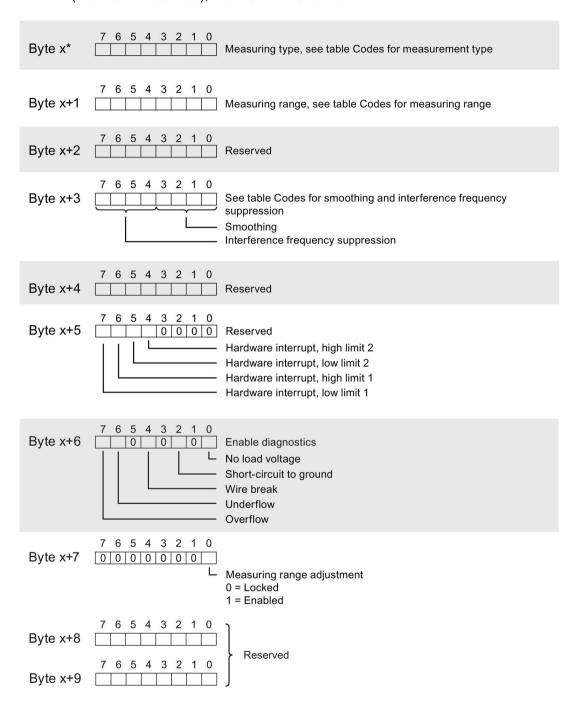
Image A-6 Structure of bytes x to x+21 for channels 0 and 1

#### Parameter (V2.0 SCALE)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 38); channel number is 0 or 1



| Byte x+10 | }                | Hardware interrupt high limit 1       |
|-----------|------------------|---------------------------------------|
| Byte x+14 | $\Bigg\}$        | Hardware interrupt low limit 1        |
| Byte x+18 | $\left. \right $ | Hardware interrupt high limit 2       |
| Byte x+22 | $\Bigg\}$        | Hardware interrupt low limit 2        |
| Byte x+26 | $\left. \right $ | Measuring range adjustment high limit |
| Byte x+28 | $\left. \right $ | Measuring range adjustment low limit  |
| Byte x+30 | }                | Scaled high nominal range limit       |
| Byte x+34 | }                | Scaled low nominal range limit        |

Image A-7 Structure of bytes x to x+37 for channels 0 and 1

#### Codes for measurement types

The following table contains all the measurement types of the analog input module with its codes. You must enter these codes at byte x (see previous figure).

Table A- 2 Codes for measurement types

| Measurement type           | Code      |
|----------------------------|-----------|
| Deactivated                | 0000 0000 |
| Voltage                    | 0000 0001 |
| Current, 4-wire transducer | 0000 0010 |
| Current, 2-wire transducer | 0000 0011 |

#### Codes for measuring ranges

The following table contains all codes for the measuring ranges of the analog input module. You must enter these codes at byte x+1 (see previous figure).

Table A-3 Codes for measuring ranges

| Measuring range | Code      |
|-----------------|-----------|
| Voltage         |           |
| ±5 V            | 0000 1000 |
| ±10 V           | 0000 1001 |
| 1 to 5 V        | 0000 1010 |
| 0 to 10 V       | 0000 1011 |
| Current         |           |
| 0 mA to 20 mA   | 0000 0010 |
| 4 mA to 20 mA   | 0000 0011 |
| ±20 mA          | 0000 0100 |

#### Codes for smoothing and interference frequency suppression

The following table contains all coding for smoothing and interference frequency suppression. You must enter these codes at byte x (see previous figure).

Table A- 4 Codes for smoothing

| Smoothing | Code |
|-----------|------|
| None      | 0000 |
| 2 times   | 0100 |
| 4 times   | 0001 |
| 8 times   | 0101 |
| 16 times  | 0010 |
| 32 times  | 0011 |

Table A- 5 Codes for interference frequency suppression

| Interference frequency suppression | Code |   |
|------------------------------------|------|---|
| 16.6 Hz (67.5 ms)                  | 0100 |   |
| 50 Hz (22.5 ms)                    | 0010 |   |
| 60 Hz (18.75 ms)                   | 0001 |   |
| 300 Hz (10 ms)                     | 0101 |   |
| 600 Hz (5 ms)                      | 0110 |   |
| 1.2 kHz (2.5 ms)                   | 0111 |   |
| 2.4 kHz (1.25 ms)                  | 1000 | • |
| 4.8 kHz (0.625 ms)                 | 1001 |   |

### Error transmitting the data record

The module always checks all values of the transmitted data record. The module applies the values from the data record only when all values have been transmitted without errors.

The WRREC instruction for writing data records returns the appropriate error codes if there are errors in the STATUS parameter.

The following table shows the module-specific error codes and their meaning for parameter data record 128.

| Error code in the STATUS pa-<br>rameter |        | US pa-     | Meaning | Solution   |   |
|---|--------|------------|---------|--|---|
|   | (hexad | ecimal)    |         |  |   |
| Byte 0                                  | Byte 1 | Byte 2     | Byte 3  |  |   |
| DF                                      | 80     | В0         | xx      | Number of the data record unknown                    | Enter valid number for data record.                                   |
| DF                                      | 80     | B1         | xx      | Length of the data record incorrect                  | Enter valid value for data record length.                             |
| DF                                      | 80     | B2         | xx      | Slot invalid or unavailable                          | Check the station to determine if the module is plugged in or pulled. |
|   |        |            |         |  | Check assigned values for the parameters of<br>the WREC instruction.  |
| DF                                      | 80     | 10         | xx      | Incorrect version or error in the header information | Correct the version, length and number of parameter blocks.           |
| DF                                      | 80     | <b>I</b> 1 | xx      | Parameter error                                      | Check the parameters of the module.                                   |

Representation of analog values



This section shows the analog values for all measuring ranges supported by the analog input module AI 2xU/I 2-/4wire HF.

#### Measured value resolution

The digitized analog value is the same for input and output values at the same nominal range. The analog values are represented as a fixed point number in the two's complement.

The resolutions 15 and 16 bits including sign are displayed. Each analog value is entered in the ACCU left-justified. The bits marked with "x" are set to "0".

Table B- 1 Resolution of the analog values

| Resolution in bits | Values  |             | Analog value       |                 |  |  |  |  |
|--------------------|---------|-------------|--------------------|-----------------|--|--|--|--|
|                    | Decimal | Hexadecimal | High byte          | Low byte        |  |  |  |  |
| 15                 | 2       | 2н          | Sign 0 0 0 0 0 0 0 | 0 0 0 0 0 0 1 x |  |  |  |  |
| 16                 | 1       | 1н          | Sign 0 0 0 0 0 0 0 | 0000001         |  |  |  |  |

# B.1 Representation of input ranges

The tables below set out the digitized representation of the input ranges by bipolar and unipolar input ranges. The resolution is 16 bits.

Table B- 2 Bipolar input ranges

| Dec.<br>value | Measured value in % |     |     |     |     |     |     |                       |    |    |                       |                       | Range |                       |                       |    |    |            |
|---------------|---------------------|-----|-----|-----|-----|-----|-----|-----------------------|----|----|-----------------------|-----------------------|-------|-----------------------|-----------------------|----|----|------------|
|               |                     | 215 | 214 | 213 | 212 | 211 | 210 | <b>2</b> <sup>9</sup> | 28 | 27 | <b>2</b> <sup>6</sup> | <b>2</b> <sup>5</sup> | 24    | <b>2</b> <sup>3</sup> | <b>2</b> <sup>2</sup> | 21 | 20 |            |
| 32767         | > 117.589           | 0   | 1   | 1   | 1   | 1   | 1   | 1                     | 1  | 1  | 1                     | 1                     | 1     | 1                     | 1                     | 1  | 1  | Overflow   |
| 32511         | 117.589             | 0   | 1   | 1   | 1   | 1   | 1   | 1                     | 0  | 1  | 1                     | 1                     | 1     | 1                     | 1                     | 1  | 1  | Overrange  |
| 27649         | 100.004             | 0   | 1   | 1   | 0   | 1   | 1   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 1  |            |
| 27648         | 100.000             | 0   | 1   | 1   | 0   | 1   | 1   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 0  |            |
| 1             | 0.003617            | 0   | 0   | 0   | 0   | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 1  |            |
| 0             | 0.000               | 0   | 0   | 0   | 0   | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 0  | Nominal    |
| -1            | -0.003617           | 1   | 1   | 1   | 1   | 1   | 1   | 1                     | 1  | 1  | 1                     | 1                     | 1     | 1                     | 1                     | 1  | 1  | range      |
| -27648        | -100.000            | 1   | 0   | 0   | 1   | 0   | 1   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 0  |            |
| -27649        | -100.004            | 1   | 0   | 0   | 1   | 0   | 0   | 1                     | 1  | 1  | 1                     | 1                     | 1     | 1                     | 1                     | 1  | 1  | Underrange |
| -32512        | -117.593            | 1   | 0   | 0   | 0   | 0   | 0   | 0                     | 1  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 0  |            |
| -32768        | < -117.593          | 1   | 0   | 0   | 0   | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0     | 0                     | 0                     | 0  | 0  | Underflow  |

Table B- 3 Unipolar input ranges

| Dec.<br>value | Measured value in % | Data word       |     |     |                        |     |     |                       |    |    |                       | Range                 |    |                       |                       |    |    |            |
|---------------|---------------------|-----------------|-----|-----|------------------------|-----|-----|-----------------------|----|----|-----------------------|-----------------------|----|-----------------------|-----------------------|----|----|------------|
|               |                     | 2 <sup>15</sup> | 214 | 213 | <b>2</b> <sup>12</sup> | 211 | 210 | <b>2</b> <sup>9</sup> | 28 | 27 | <b>2</b> <sup>6</sup> | <b>2</b> <sup>5</sup> | 24 | <b>2</b> <sup>3</sup> | <b>2</b> <sup>2</sup> | 21 | 20 |            |
| 32767         | > 117.589           | 0               | 1   | 1   | 1                      | 1   | 1   | 1                     | 1  | 1  | 1                     | 1                     | 1  | 1                     | 1                     | 1  | 1  | Overflow   |
| 32511         | 117.589             | 0               | 1   | 1   | 1                      | 1   | 1   | 1                     | 0  | 1  | 1                     | 1                     | 1  | 1                     | 1                     | 1  | 1  | Overrange  |
| 27649         | 100.004             | 0               | 1   | 1   | 0                      | 1   | 1   | 0                     | 0  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 1  |            |
| 27648         | 100.000             | 0               | 1   | 1   | 0                      | 1   | 1   | 0                     | 0  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 0  | Nominal    |
| 1             | 0.003617            | 0               | 0   | 0   | 0                      | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 1  | range      |
| 0             | 0.000               | 0               | 0   | 0   | 0                      | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 0  |            |
| -1            | -0.003617           | 1               | 1   | 1   | 1                      | 1   | 1   | 1                     | 1  | 1  | 1                     | 1                     | 1  | 1                     | 1                     | 1  | 1  | Underrange |
| -4864         | -17.593             | 1               | 1   | 1   | 0                      | 1   | 1   | 0                     | 1  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 0  |            |
| -32768        | < -17.593           | 1               | 0   | 0   | 0                      | 0   | 0   | 0                     | 0  | 0  | 0                     | 0                     | 0  | 0                     | 0                     | 0  | 0  | Underflow  |

# B.2 Representation of analog values in voltage measuring ranges

The following tables list the decimal and hexadecimal values (codes) of the possible voltage measuring ranges.

Table B- 4 Voltage measuring range ±10 V and ±5 V

| Values |      | Voltage measuring | range      | Range         |
|--------|------|-------------------|------------|---------------|
| Dec.   | Hex. | ±10 V             | ±5 V       |               |
| 32767  | 7FFF | > 11.759 V        | > 5.879 V  | Overflow      |
| 32511  | 7EFF | 11.759 V          | 5.879 V    | Overrange     |
| 27649  | 6C01 |                   |            |               |
| 27648  | 6C00 | 10 V              | 5 V        | Nominal range |
| 20736  | 5100 | 7.5 V             | 3.75 V     |               |
| 1      | 1    | 361.7 μV          | 180.8 μV   |               |
| 0      | 0    | 0 V               | 0 V        |               |
| -1     | FFFF |                   |            |               |
| -20736 | AF00 | -7.5 V            | -3.75 V    |               |
| -27648 | 9400 | -10 V             | -5 V       |               |
| -27649 | 93FF |                   |            | Underrange    |
| -32512 | 8100 | -11.759 V         | -5.879 V   |               |
| -32768 | 8000 | < -11.759 V       | < -5.879 V | Underflow     |

-32768

8000

Values Voltage measuring range Range Dec. 0 to 10 V Hex. 1 to 5 V > 5.704 V 32767 7FFF > 11.759 V Overflow 32511 7EFF 5.704 V 11.759 V Overrange 27649 6C01 27648 6C00 5 V 10 V Nominal range 20736 5100 4 V 7.5 V 1 1 1 V + 144.7 µV 361.7 µV 0 0 1 V 0 V FFFF -1 Underrange -4864 ED00 0.296 V -1.759 V

< -1.759 V

Underflow

Table B- 5 Voltage measuring range 1 V to 5 V and 0 V to 10 V

## B.3 Representation of analog values in the current measuring ranges

< 0.296 V

The following tables list the decimal and hexadecimal values (codes) of the possible current measuring ranges.

Table B- 6 Current measuring range ±20 mA

| Values |      | Current measuring range | Range         |
|--------|------|-------------------------|---------------|
| Dec.   | Hex. | ±20 mA                  |               |
| 32767  | 7FFF | > 23.52 mA              | Overflow      |
| 32511  | 7EFF | 23.52 mA                | Overrange     |
| 27649  | 6C01 |                         |               |
| 27648  | 6C00 | 20 mA                   | Nominal range |
| 20736  | 5100 | 15 mA                   |               |
| 1      | 1    | 723.4 nA                |               |
| 0      | 0    | 0 mA                    |               |
| -1     | FFFF |                         |               |
| -20736 | AF00 | -15 mA                  |               |
| -27648 | 9400 | -20 mA                  |               |
| -27649 | 93FF |                         | Underrange    |
| -32512 | 8100 | -23.52 mA               |               |
| -32768 | 8000 | < -23.52 mA             | Underflow     |

Table B- 7 Current measuring ranges 0 to 20 mA and 4 to 20 mA

| Values |      | Current measuring | ng range        | Range         |
|--------|------|-------------------|-----------------|---------------|
| Dec.   | Hex. | 0 to 20 mA*       | 4 to 20 mA      |               |
| 32767  | 7FFF | > 23.52 mA        | > 22.81 mA      | Overflow      |
| 32511  | 7EFF | 23.52 mA          | 22.81 mA        | Overrange     |
| 27649  | 6C01 |                   |                 |               |
| 27648  | 6C00 | 20 mA             | 20 mA           | Nominal range |
| 20736  | 5100 | 15 mA             | 16 mA           |               |
| 1      | 1    | 723.4 nA          | 4 mA + 578.7 nA |               |
| 0      | 0    | 0 mA              | 4 mA            |               |
| -1     | FFFF |                   |                 | Underrange    |
| -4864  | ED00 | -3.52 mA          | 1.185 mA        |               |
| -32768 | 8000 | < -3.52 mA        | < 1.185 mA      | Underflow     |

<sup>\*</sup> For measurement type "2-wire transducer", negative values are not possible for the range "0 to 20 mA". Therefore, no underrange or underflow exists here.