## **SIEMENS**

## Data sheet

## 6ES7515-2AM01-0AB0

SIMATIC S7-1500, CPU 1515-2 PN, Central processing unit with work memory 500 KB for Program and 3 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 30 ns bit performance, SIMATIC Memory Card required



General information	
Product type designation	CPU 1515-2 PN
HW functional status	FS03
Firmware version	V2.8
Product function	
● I&M data	Yes; I&M0 to I&M3
• Isochronous mode	Yes; Distributed and central; with minimum OB $6x$ cycle of $500~\mu s$ (distributed) and 1 ms (central)
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated as of version</li> </ul>	V16 (FW V2.8) / V13 (FW V1.5) or higher
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	6.1 cm
Control elements	
Number of keys	6
Mode selector switch	1

Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
Mains/voltage failure stored energy time	5 ms
Repeat rate, min.	1/s
·	
Input current Current consumption (rated value)	0.8 A
Inrush current, max.	2.4 A; Rated value
12t	0.02 A²·s
T	0.02 A-S
Power	
Infeed power to the backplane bus	12 W
Power consumption from the backplane bus	6.2 W
(balanced)	
Power loss	
Power loss, typ.	6.3 W
Momony	
Memory  Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	163
• integrated (for program)	500 kbyte
	3 Mbyte
• integrated (for data)  Load memory	3 Misyle
	32 Gbyte
Plug-in (SIMATIC Memory Card), max.      Packup	32 Gbyte
Backup	Yes
maintenance-free	165
CPU processing times	
for bit operations, typ.	30 ns
for word operations, typ.	36 ns
for fixed point arithmetic, typ.	48 ns
for floating point arithmetic, typ.	192 ns
CPU-blocks	
Number of elements (total)	6 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	3 Mbyte; For DBs with absolute addressing, the max. size is 64 KB

FB	
Number range	0 65 535
● Size, max.	500 kbyte
FC	
Number range	0 65 535
• Size, max.	500 kbyte
ОВ	
• Size, max.	500 kbyte
Number of free cycle OBs	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
Number of delay alarm OBs	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20; With minimum OB 3x cycle of 500 μs
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	2
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
<ul> <li>Number of diagnostic alarm OBs</li> </ul>	1
Nesting depth	
• per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	

Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Extended retentive data area (incl. timers, counters, flags), max.	3 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
Number, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
• per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
<ul><li>Outputs</li></ul>	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
● Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	2
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots

Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
● on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	2
1. Interface	
Interface types	
<ul><li>Number of ports</li></ul>	2
• integrated switch	Yes
• RJ 45 (Ethernet)	Yes; X1
Protocols	
IP protocol	Yes; IPv4
<ul> <li>PROFINET IO Controller</li> </ul>	Yes
PROFINET IO Device	Yes
<ul> <li>SIMATIC communication</li> </ul>	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— MRP	Yes; MRP Automanager acc. to IEC 62439-2 Edition 2.0; MRP Manager; MRP Client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	256; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET

— Of which IO devices with IRT, max.	64
<ul> <li>Number of connectable IO Devices for RT,</li> </ul>	256
max.	
— of which in line, max.	256
<ul> <li>Number of IO Devices that can be</li> </ul>	8; in total across all interfaces
simultaneously activated/deactivated, max.	
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO
11.14.65.45.107	devices, and on the quantity of configured user data
Update time for IRT	OFO up to 4 year Notes in the case of IDT with incohurance world
— for send cycle of 250 μs	250 $\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 $\mu s$ of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul><li>— With IRT and parameterization of "odd" send cycles</li></ul>	Update time = set "odd" send clock (any multiple of 125 $\mu$ s: 375 $\mu$ s, 625 $\mu$ s 3 875 $\mu$ s)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— IRT	Yes
— MRP	Yes; MRP Automanager acc. to IEC 62439-2 Edition 2.0; MRP Manager; MRP Client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes; per user program
— Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
<ul> <li>Asset management record</li> </ul>	Yes; per user program
2. Interface	
Interface types	
Number of ports	1

integrated switch	No
• RJ 45 (Ethernet)	Yes; X2
Protocols	·
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	No
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— Direct data exchange	No
— IRT	No
— MRP	No
— MRPD	No
— PROFlenergy	Yes; per user program
<ul> <li>Prioritized startup</li> </ul>	No
— Number of connectable IO Devices, max.	32; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	32
— of which in line, max.	32
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for RT	
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— IRT	No
— MRP	No
— MRPD	No

— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
Asset management record	Yes; per user program

Interface types	
RJ 45 (Ethernet)	
● 100 Mbps	Yes
<ul> <li>Autonegotiation</li> </ul>	Yes
<ul> <li>Autocrossing</li> </ul>	Yes
<ul> <li>Industrial Ethernet status LED</li> </ul>	Yes

Number of connections	
Number of connections, max.	192; via integrated interfaces of the CPU and connected CPs /
- Number of Confections, Max.	CMs
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
<ul> <li>Number of connections via integrated interfaces</li> </ul>	108
<ul> <li>Number of S7 routing paths</li> </ul>	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
— Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
<ul> <li>Number of stations in the ring, max.</li> </ul>	50
SIMATIC communication	
S7 communication, as server	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
<ul> <li>User data per job, max.</li> </ul>	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>several passive connections per port, supported</li> </ul>	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	No
• SNMP	Yes

Protocols

• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes
OPC UA client	Yes
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of connections, max.	10
<ul> <li>Number of nodes of the client interfaces, max.</li> </ul>	2 000
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_Rea dList/OPC_UA_WriteList, max.</li> </ul>	300
<ul> <li>Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul><li>— Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li></ul>	100
<ul> <li>Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_ UA_MethodCall), max.</li> </ul>	1
<ul> <li>Number of simultaneous calls of the client instructions</li> <li>OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.</li> </ul>	5
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul> <li>Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li> </ul>	20
OPC UA server	Yes; Data access (read, write, subscribe), method call, custom address space
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of sessions, max.	48
— Number of accessible variables, max.	100 000
— Number of registerable nodes, max.	20 000

<ul> <li>Number of subscriptions per session, max.</li> </ul>	20
<ul><li>— Sampling interval, min.</li></ul>	100 ms
— Publishing interval, min.	200 ms
<ul> <li>Number of server methods, max.</li> </ul>	50
<ul> <li>Number of inputs/outputs per server</li> </ul>	20
method, max.	
<ul> <li>Number of monitored items, max.</li> </ul>	2 000; for 1 s sampling interval and 1 s send interval
<ul> <li>Number of server interfaces, max.</li> </ul>	10; or 20, depending on type of server interface
<ul> <li>Number of nodes for user-defined server</li> </ul>	5 000
interfaces, max.	
Further protocols	
• MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	04
Number of login stations for message functions, max.	64
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the  "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN,	5 000
max.	
Number of simultaneously active program alarms	
Number of program alarms	800
<ul> <li>Number of alarms for system diagnostics</li> </ul>	200
<ul> <li>Number of alarms for motion technology</li> </ul>	160
objects	
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering
· · · · · · · · · · · · · · · · · · ·	systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
<ul><li>Number of variables, max.</li></ul>	
— of which status variables, max.	200; per job

• Forcing, variables

• Number of variables, max.

- of which control variables, max.

Peripheral inputs/outputs

200; per job

200

Forcing

Diagnostic buffer		
• present	Yes	
<ul> <li>Number of entries, max.</li> </ul>	3 200	
— of which powerfail-proof	500	
Traces		
Number of configurable Traces	4; Up to 512 KB of data per trace are possible	

Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes

Motion Control  Yes; Note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER  • Number of available Motion Control resources for technology objects  • Required Motion Control resources  — per speed-controlled axis — per prositioning axis — per external encoder — per output cam — per cam track — per probe  • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Satep • PID_Temp  Counting and measuring • High-speed counter  Yes; Universal PID controller with integrated optimization for temperature	Supported technology objects		
Number of available Motion Control resources for technology objects  Required Motion Control resources  — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)  Controller  PID_Compact  PID_Compact PID_Temp  Counting and measuring  2 400  2 400  2 400  2 400  40  40  40  40  40  41  42  40  40  40  40  40  41  42  44  45  46  47  48  49  40  40  40  40  40  40  40  40  40	Motion Control	Yes; Note: The number of axes affects the cycle time of the PLC	
for technology objects  Required Motion Control resources  — per speed-controlled axis  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per robe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Yes; PID controller with integrated optimization for valves  Yes; PID controller with integrated optimization for temperature  Counting and measuring		program; selection guide via the TIA Selection Tool or SIZER	
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  PID_Compact  PID_Compact  PID_Step  PID-Temp  Yes; Universal PID controller with integrated optimization for valves  Yes; PID controller with integrated optimization for temperature  Counting and measuring		2 400	
- per speed-controlled axis - per positioning axis - per synchronous axis - per external encoder - per output cam - per cam track - per cam track - per probe - Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value) - PID_Compact - PID_Step - PID-Temp - PID-Temp - Counting and measuring - 80 - 90 - 80 - 90 - 90 - 90 - 90 - 90 - 90 - 90 - 9	for technology objects		
— per positioning axis — per synchronous axis — per external encoder — per output cam — per output cam — per cam track — per probe 40  • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	<ul> <li>Required Motion Control resources</li> </ul>		
— per synchronous axis — per external encoder — per output cam — per cam track — per probe 40  • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	— per speed-controlled axis	40	
- per external encoder - per output cam - per cam track - per probe 40  • Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Step • PID-Temp  Yes; Universal PID controller with integrated optimization for valves  Yes; PID controller with integrated optimization for temperature  Counting and measuring	<ul><li>per positioning axis</li></ul>	80	
- per output cam - per cam track - per probe  • Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Satep • PID-Temp  Yes; Universal PID controller with integrated optimization for valves  • PID-Temp  Yes; PID controller with integrated optimization for temperature  Counting and measuring	— per synchronous axis	160	
- per cam track - per probe  • Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller • PID_Compact • PID_Sastep • PID-Temp  PID-Temp  Yes; PID controller with integrated optimization for valves  Yes; PID controller with integrated optimization for temperature	— per external encoder	80	
<ul> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> <li>PID_Compact</li> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID_Temp</li> <li>Yes; PID controller with integrated optimization for valves</li> <li>Yes; PID controller with integrated optimization for temperature</li> </ul>	— per output cam	20	
<ul> <li>Positioning axis         <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller         <ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> </ul> </li> <li>Counting and measuring</li> <li>To controller with integrated optimization for valves and measuring</li> <li>PID controller with integrated optimization for temperature</li> </ul>	— per cam track	160	
<ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> <li>PID_Compact</li> <li>PID_Step</li> <li>PID-Temp</li> <li>Yes; Universal PID controller with integrated optimization for valves</li> <li>PID-Temp</li> <li>Yes; PID controller with integrated optimization for temperature</li> </ul>	— per probe	40	
control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp  Yes; Universal PID controller with integrated optimization for valves  Yes; PID controller with integrated optimization for temperature  Counting and measuring	<ul> <li>Positioning axis</li> </ul>		
<ul> <li>— Number of positioning axes at motion control cycle of 8 ms (typical value)</li> <li>Controller         <ul> <li>● PID_Compact</li> <li>● PID_3Step</li> <li>● PID-Temp</li> </ul> </li> <li>Controller with integrated optimization for valves</li> <li>● PID-Temp</li> <li>Yes; PID controller with integrated optimization for temperature</li> </ul> <li>Counting and measuring</li>	<ul> <li>Number of positioning axes at motion</li> </ul>	7	
control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring	control cycle of 4 ms (typical value)		
Controller         ● PID_Compact       Yes; Universal PID controller with integrated optimization         ● PID_3Step       Yes; PID controller with integrated optimization for valves         ● PID-Temp       Yes; PID controller with integrated optimization for temperature         Counting and measuring	<ul> <li>Number of positioning axes at motion</li> </ul>	14	
<ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> <li>Yes; Universal PID controller with integrated optimization</li> <li>Yes; PID controller with integrated optimization for valves</li> <li>Yes; PID controller with integrated optimization for temperature</li> </ul> Counting and measuring	control cycle of 8 ms (typical value)		
<ul> <li>◆ PID_3Step</li> <li>◆ PID-Temp</li> <li>Yes; PID controller with integrated optimization for valves</li> <li>Yes; PID controller with integrated optimization for temperature</li> </ul> Counting and measuring	Controller		
PID-Temp     Yes; PID controller with integrated optimization for temperature  Counting and measuring	<ul><li>PID_Compact</li></ul>	Yes; Universal PID controller with integrated optimization	
Counting and measuring	• PID_3Step	Yes; PID controller with integrated optimization for valves	
	<ul><li>PID-Temp</li></ul>	Yes; PID controller with integrated optimization for temperature	
High-speed counter     Yes	Counting and measuring		
	High-speed counter	Yes	

bient conditions	
mbient temperature during operation	
horizontal installation, min.	0 °C
• horizontal installation, max.	60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off

<ul> <li>vertical installation, min.</li> </ul>	0 °C	
• vertical installation, max.	40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off	
Ambient temperature during storage/transportation		
• min.	-40 °C	
• max.	70 °C	
Altitude during operation relating to sea level		
<ul> <li>Installation altitude above sea level, max.</li> </ul>	5 000 m; Restrictions for installation altitudes > 2 000 m, see	
	manual	
Configuration	manual	
Configuration Programming	manual	
	manual	
Programming	Yes	
Programming Programming language		
Programming Programming language — LAD	Yes	

Yes

Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
<ul> <li>Copy protection</li> </ul>	Yes
<ul> <li>Block protection</li> </ul>	Yes
Access protection	
Dassword for display	Ves

Password for display	Yes
Protection level: Write protection	Yes
Protection level: Read/write protection	Yes
Protection level: Complete protection	Yes

Cycle time monitoring		
• lower limit	adjustable minimum cycle time	
• upper limit	adjustable maximum cycle time	

Dimensions	
Width	70 mm
Height	147 mm
Depth	129 mm

Weights		
Weight, approx.	830 g	